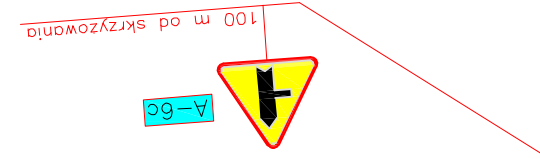
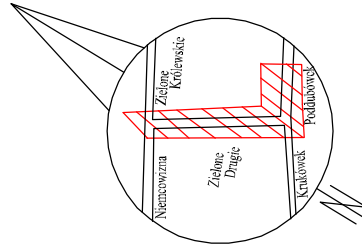
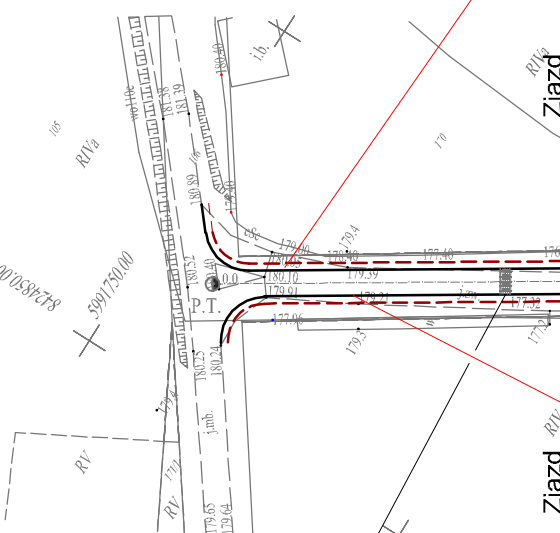


PROJEKT STAŁEJ ORGANIZACJI RUCHU

SKALA 1:1000



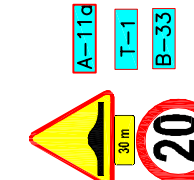
100 m od skrzyżowania



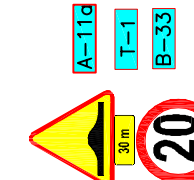
Próg zwalniający km 0+040
długość - 3,5m,
szerokość - 1,5m,
wysokość - 0,07m,
promień wycinka koła = 4,1m.



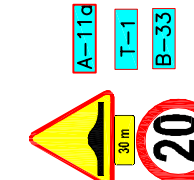
100 m od skrzyżowania



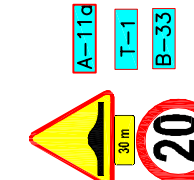
km 0+010



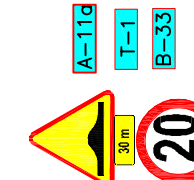
km 0+010



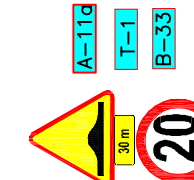
km 0+010



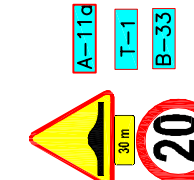
km 0+010



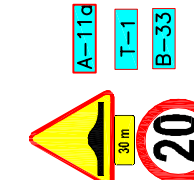
km 0+010



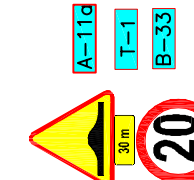
km 0+010



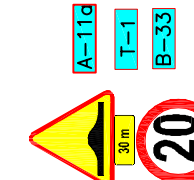
km 0+010



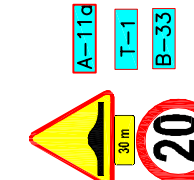
km 0+010



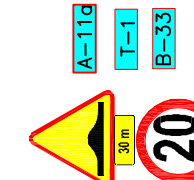
km 0+010



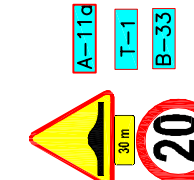
km 0+010



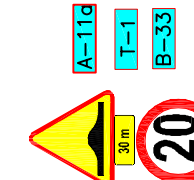
km 0+010



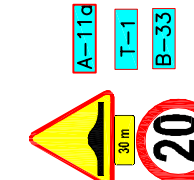
km 0+010



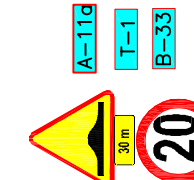
km 0+010



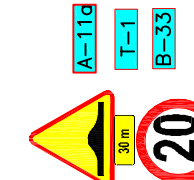
km 0+010



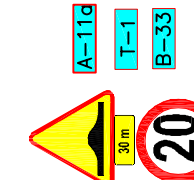
km 0+010



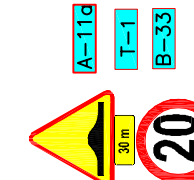
km 0+010



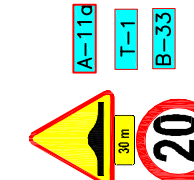
km 0+010



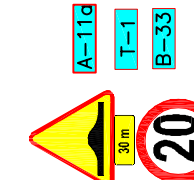
km 0+010



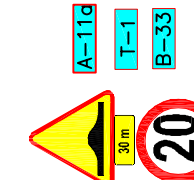
km 0+010



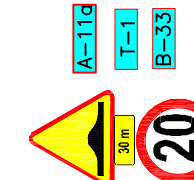
km 0+010



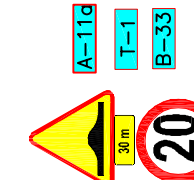
km 0+010



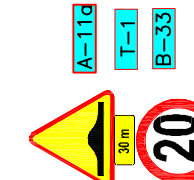
km 0+010



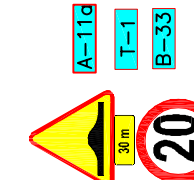
km 0+010



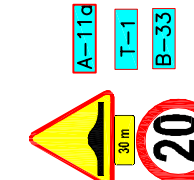
km 0+010



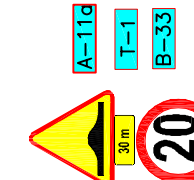
km 0+010



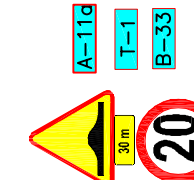
km 0+010



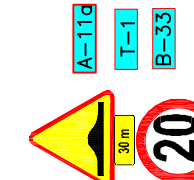
km 0+010



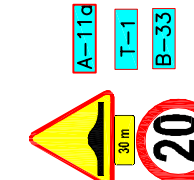
km 0+010



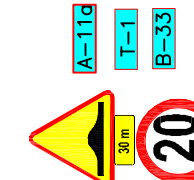
km 0+010



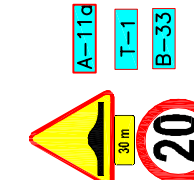
km 0+010



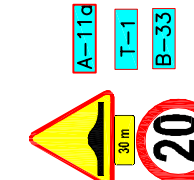
km 0+010



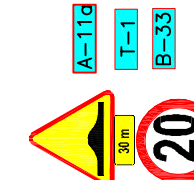
km 0+010



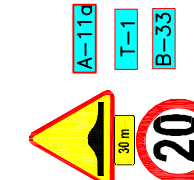
km 0+010



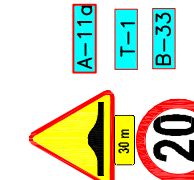
km 0+010



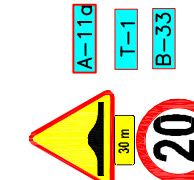
km 0+010



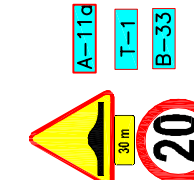
km 0+010



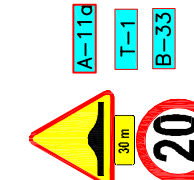
km 0+010



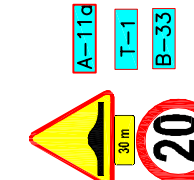
km 0+010



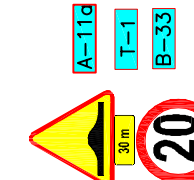
km 0+010



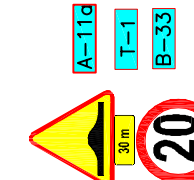
km 0+010



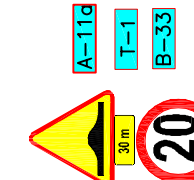
km 0+010



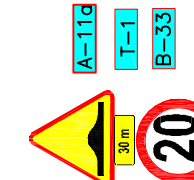
km 0+010



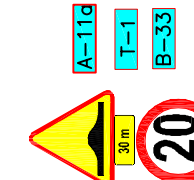
km 0+010



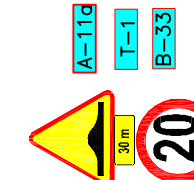
km 0+010



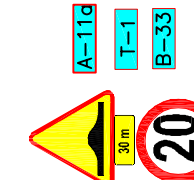
km 0+010



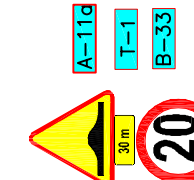
km 0+010



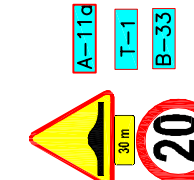
km 0+010



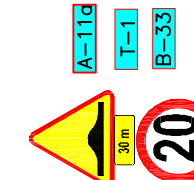
km 0+010



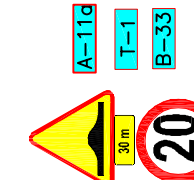
km 0+010



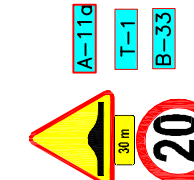
km 0+010



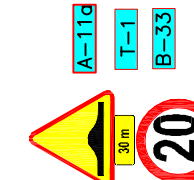
km 0+010



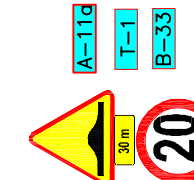
km 0+010



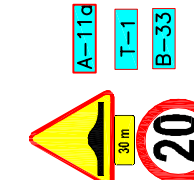
km 0+010



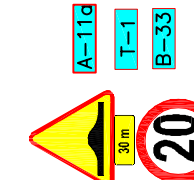
km 0+010



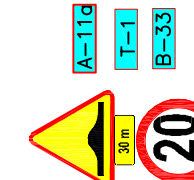
km 0+010



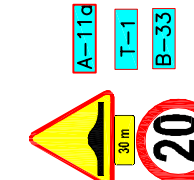
km 0+010



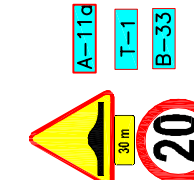
km 0+010



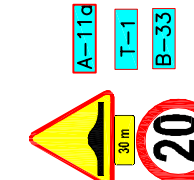
km 0+010



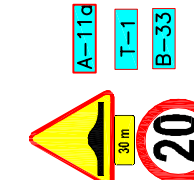
km 0+010



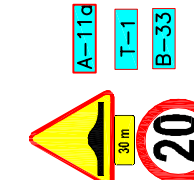
km 0+010



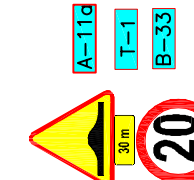
km 0+010



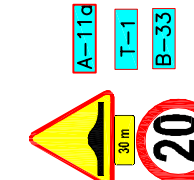
km 0+010



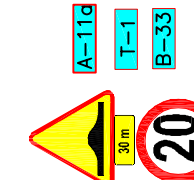
km 0+010



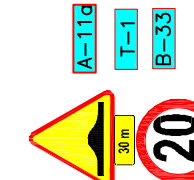
km 0+010



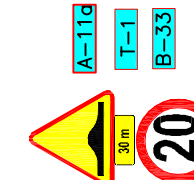
km 0+010



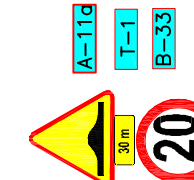
km 0+010



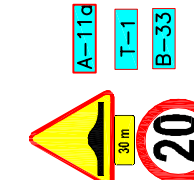
km 0+010



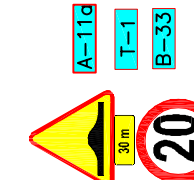
km 0+010



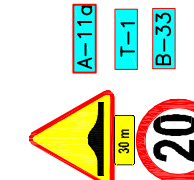
km 0+010



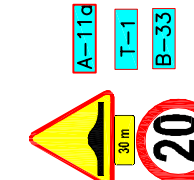
km 0+010



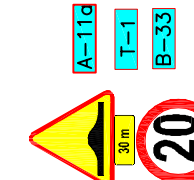
km 0+010



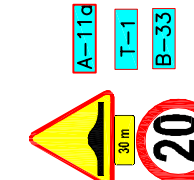
km 0+010



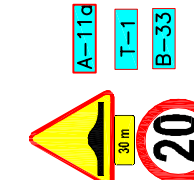
km 0+010



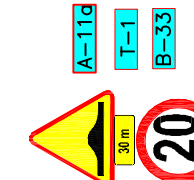
km 0+010



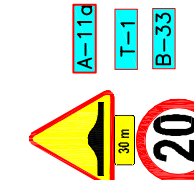
km 0+010



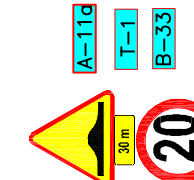
km 0+010



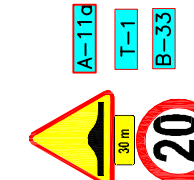
km 0+010



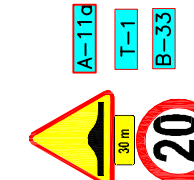
km 0+010



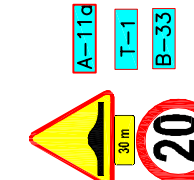
km 0+010



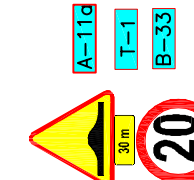
km 0+010



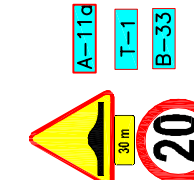
km 0+010



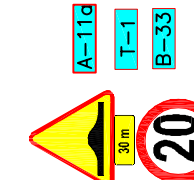
km 0+010



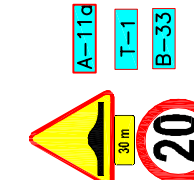
km 0+010



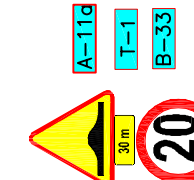
km 0+010



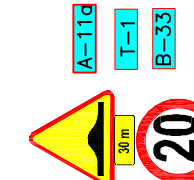
km 0+010



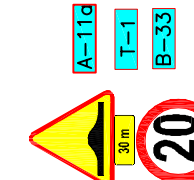
km 0+010



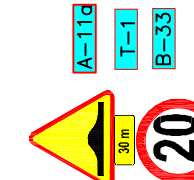
km 0+010



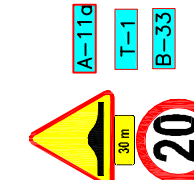
km 0+010



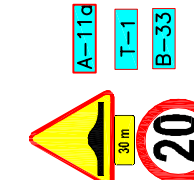
km 0+010



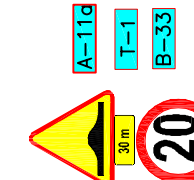
km 0+010



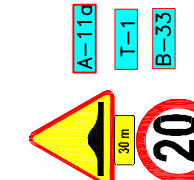
km 0+010



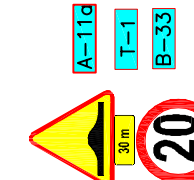
km 0+010



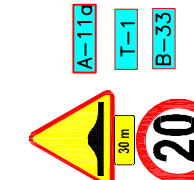
km 0+010



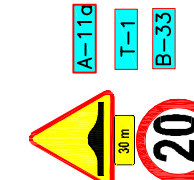
km 0+010



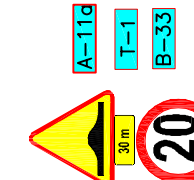
km 0+010



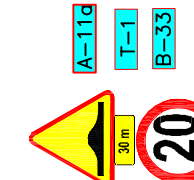
km 0+010



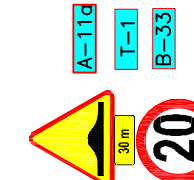
km 0+010



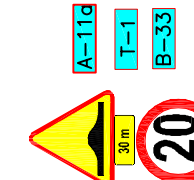
km 0+010



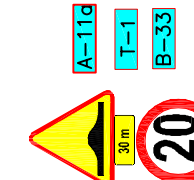
km 0+010



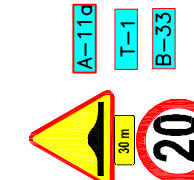
km 0+010



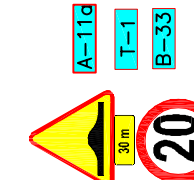
km 0+010



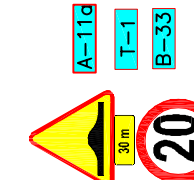
km 0+010



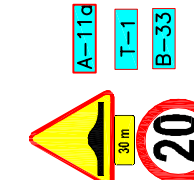
km 0+010



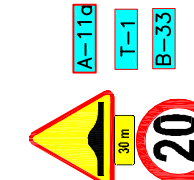
km 0+010



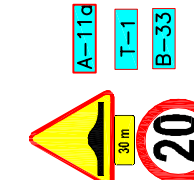
km 0+010



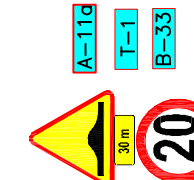
km 0+010



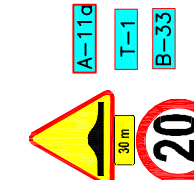
km 0+010



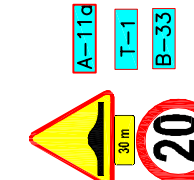
km 0+010



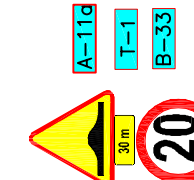
km 0+010



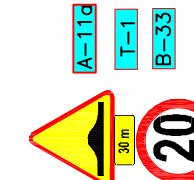
km 0+010



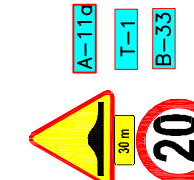
km 0+010



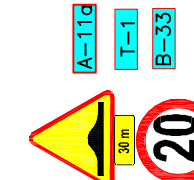
km 0+010



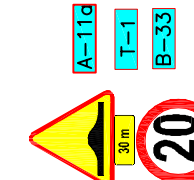
km 0+010



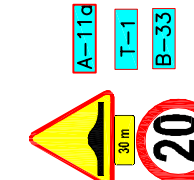
km 0+010



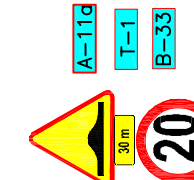
km 0+010



km 0+010



km 0+010



km 0+010

